The task consists in stacking simple bricks. The reward is proportional to the height of the tower.

As the height of the tower increases, the probability of failure increases as well: we want the robot to be risk-aware.

We will develop a pessimistic reinforcement algorithm, which is robust against failures.
We will use Darias

Goals:
- Learn and implement a novel RL algorithm
- Work with a robot
- Have fun :)

Risk-Aware Reinforcement Learning