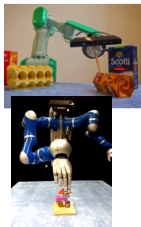# Semi-Autonomous Tele-Operation

Your task:

use our brand new Haption (Master)

to control one of our robots (Slave)

But there is more to it:

we want to assist the operator (Force-Feedback)

based on a learned policy (Imitation Learning)