

Control and Learning for a Bipedal Robot

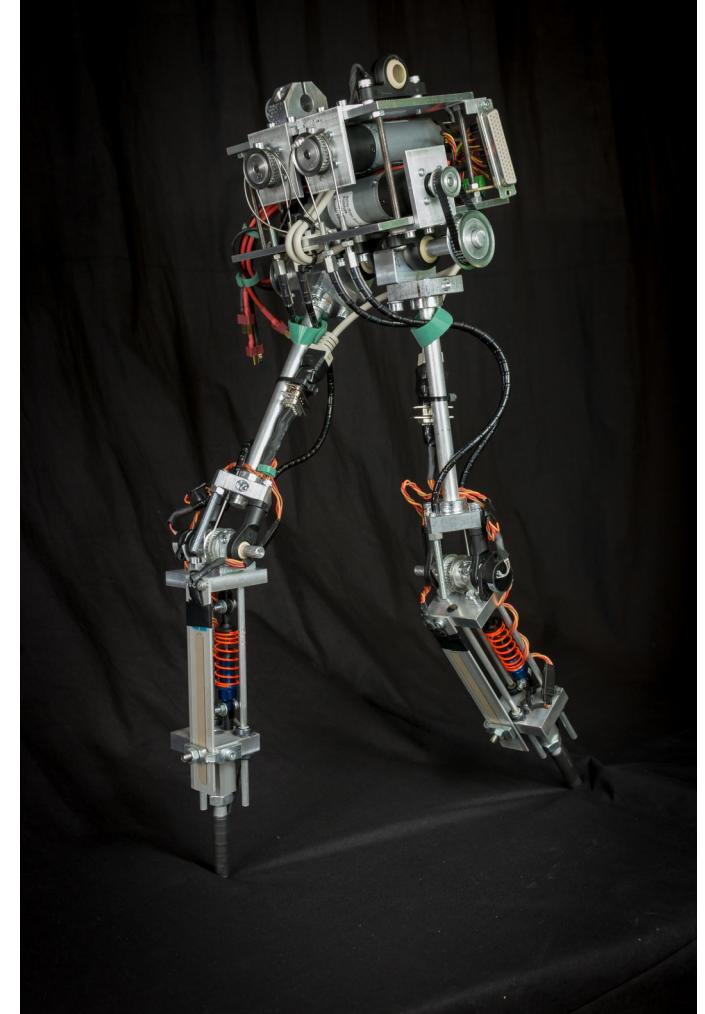
Part 1: Design controller for walking (1 or 2 from literature)

Part 2: Learn to walk (using ML)

Inter-disciplinary project:

- Roberto Calandra (Informatik - IAS)
- Philipp Beckerle (Maschinenbau - IMS)
- Sasha Voloshina (Sport Science - LaufLabor)

At the end: Publish a paper in an international conference



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